

## Math S-21b – Lecture #15 Notes

In this class we'll apply the **Spectral Theorem** and the **Principal Axes Theorem** to understand **quadratic forms**. We'll also discuss the **Singular Value Decomposition** of any matrix.

**Definition:** A quadratic form is a homogeneous polynomial of degree 2, i.e. a polynomial function  $q(\mathbf{x})$  such that  $q(t\mathbf{x}) = t^2 q(\mathbf{x})$ , a pure quadratic expression in  $n$  variables.. For example:

$$(a) \quad q(x, y) = 8x^2 - 4xy + 5y^2$$

$$(b) \quad q(x_1, x_2, x_3) = x_1^2 - 2x_2^2 + 4x_3^2 + 2x_1x_2 - x_1x_3 + 4x_2x_3$$

**Observation:** Any quadratic form can be expressed as  $\mathbf{x}^T \mathbf{A} \mathbf{x}$  where  $\mathbf{x}$  is an  $n \times 1$  (column) vector and  $\mathbf{A}$  is a symmetric  $n \times n$  matrix. For example:

$$(a) \quad q(x, y) = 8x^2 - 4xy + 5y^2 = \begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} 8 & -2 \\ -2 & 5 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \mathbf{x}^T \mathbf{A} \mathbf{x}$$

$$(b) \quad q(x_1, x_2, x_3) = x_1^2 - 2x_2^2 + 4x_3^2 + 2x_1x_2 - x_1x_3 + 4x_2x_3 = \begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix} \begin{bmatrix} 1 & 1 & -\frac{1}{2} \\ 1 & -2 & 2 \\ -\frac{1}{2} & 2 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \mathbf{x}^T \mathbf{A} \mathbf{x}$$

**Principal Axes Theorem:** Any quadratic form  $q(\mathbf{x}) = \mathbf{x}^T \mathbf{A} \mathbf{x}$  may be expressed without cross terms in new coordinates via an orthonormal change of basis. That is, there exists an orthonormal basis  $\mathcal{B} = \{\mathbf{u}_1, \dots, \mathbf{u}_n\}$  and scalars  $\{\lambda_1, \dots, \lambda_n\}$  such that if  $\{y_1, \dots, y_n\}$  are the coordinates relative to the basis  $\mathcal{B} = \{\mathbf{u}_1, \dots, \mathbf{u}_n\}$ , then  $q(\mathbf{x}) = \mathbf{x}^T \mathbf{A} \mathbf{x} = \mathbf{y}^T \mathbf{D} \mathbf{y} = \lambda_1 y_1^2 + \dots + \lambda_n y_n^2$ .

**Proof:** By the Spectral Theorem, since  $\mathbf{A}$  is symmetric it is orthogonally diagonalizable, i.e. it has real eigenvalues  $\{\lambda_1, \dots, \lambda_n\}$  and associated orthonormal eigenvectors  $\mathcal{B} = \{\mathbf{u}_1, \dots, \mathbf{u}_n\}$  for the matrix  $\mathbf{A}$  such that if is

the orthogonal change of basis matrix  $\mathbf{S} = \begin{bmatrix} \uparrow & & \uparrow \\ \mathbf{u}_1 & \cdots & \mathbf{u}_n \\ \downarrow & & \downarrow \end{bmatrix}$ , then  $[\mathbf{A}]_{\mathcal{B}} = \mathbf{S}^{-1} \mathbf{A} \mathbf{S} = \mathbf{S}^T \mathbf{A} \mathbf{S} = \mathbf{D} = \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix}$ , a

diagonal matrix. We may therefore write  $\mathbf{A} = \mathbf{S} \mathbf{D} \mathbf{S}^T$ , so

$$q(\mathbf{x}) = \mathbf{x}^T \mathbf{A} \mathbf{x} = \mathbf{x}^T \mathbf{S} \mathbf{D} \mathbf{S}^T \mathbf{x} = (\mathbf{S}^T \mathbf{x})^T \mathbf{D} (\mathbf{S}^T \mathbf{x}) = (\mathbf{S}^{-1} \mathbf{x})^T \mathbf{D} (\mathbf{S}^{-1} \mathbf{x}) = \mathbf{y}^T \mathbf{D} \mathbf{y} = \lambda_1 y_1^2 + \dots + \lambda_n y_n^2.$$

**Definitions:** A quadratic form  $q(\mathbf{x}) = \mathbf{x}^T \mathbf{A} \mathbf{x}$  with symmetric matrix  $\mathbf{A}$  is called:

- (a) **positive definite** if all of the eigenvalues  $\{\lambda_1, \dots, \lambda_n\}$  are strictly positive.
- (b) **negative definite** if all of the eigenvalues  $\{\lambda_1, \dots, \lambda_n\}$  are strictly negative.
- (c) **positive semi-definite** if all of the eigenvalues  $\{\lambda_1, \dots, \lambda_n\}$  are greater than or equal to 0.
- (d) **negative semi-definite** if all of the eigenvalues  $\{\lambda_1, \dots, \lambda_n\}$  are less than or equal to 0.
- (e) **indefinite** if some eigenvalues are positive and some or negative (and some may be equal to 0).

Some immediate applications are in **identifying the graphs of quadratic functions**  $q(x, y)$  and **identifying level sets** of the form  $q(x, y) = C$  (conic sections such as ellipses and hyperbolas) and  $q(x, y, z) = C$  (quadric sections such as ellipsoids and hyperboloids of one or two sheets).

**Example:** The graph of the function  $q(x, y) = 8x^2 - 4xy + 5y^2 = \begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} 8 & -2 \\ -2 & 5 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \mathbf{x}^T \mathbf{A} \mathbf{x}$  can be easily

identified by calculating the eigenvalues of  $\mathbf{A}$  as  $\lambda_1 = 9$  and  $\lambda_2 = 4$  with orthonormal eigenbasis

$\mathbf{u}_1 = \frac{1}{\sqrt{5}} \begin{bmatrix} 2 \\ -1 \end{bmatrix}$ ,  $\mathbf{u}_2 = \frac{1}{\sqrt{5}} \begin{bmatrix} 1 \\ 2 \end{bmatrix}$ . In (rotated) coordinates  $\{u, v\}$  relative to this new basis, the graph  $q = 9u^2 + 4v^2$

can be identified as an (upward, rotated) **paraboloid**. Similarly, the level set  $q(x, y) = 8x^2 - 4xy + 5y^2 = 36$

may be re-expressed as  $q = 9u^2 + 4v^2 = 36$  or  $\left(\frac{u}{2}\right)^2 + \left(\frac{v}{3}\right)^2 = 1$ , a (rotated) **ellipse** with semi-major axis 3

and semi-minor axis 2. Note that the longer axis corresponds to the *smaller* eigenvalue (slower growth) and the shorter axis corresponds to the *larger* eigenvalue (faster growth) to reach the given level set.

In the case of a level set of a **quadratic function in 3 variables**, if  $q(x_1, x_2, x_3) = C > 0$ . If the signs of the eigenvalues are  $\{+, +, +\}$ , the level set will be a (rotated) **ellipsoid**. If the signs of the eigenvalues are  $\{+, +, -\}$ , the level set will be a (rotated) **hyperboloid of one sheet**. If the signs of the eigenvalues are  $\{+, -, -\}$ , the level set will be a (rotated) **hyperboloid of two sheets**.

### Singular Values and the Singular Value Decomposition (SVD)

Given any  $m \times n$  matrix  $\mathbf{A}$ , it's possible to find an orthonormal basis  $\mathcal{B} = \{\mathbf{u}_1, \dots, \mathbf{u}_n\}$  for the domain ( $\mathbf{R}^n$ ) as well as an orthonormal basis  $\mathcal{C} = \{\mathbf{w}_1, \dots, \mathbf{w}_m\}$  for the codomain ( $\mathbf{R}^m$ ) such that the images  $\{\mathbf{A}\mathbf{u}_1, \dots, \mathbf{A}\mathbf{u}_n\}$  are orthogonal (some may be  $\mathbf{0}$ ) and are scalar multiples, respectively, of the vectors  $\{\mathbf{w}_1, \dots, \mathbf{w}_m\}$  in the codomain. The scalars  $\|\mathbf{A}\mathbf{u}_i\| = \sigma_i$  are called the **singular values** of the matrix  $\mathbf{A}$  (and the linear transformation that it represents).

This observation follows by considering the symmetric  $n \times n$  matrix  $\mathbf{A}^T \mathbf{A}$ . By the Spectral Theorem, this matrix yields an orthonormal basis of eigenvectors  $\mathcal{B} = \{\mathbf{u}_1, \dots, \mathbf{u}_n\}$  with real eigenvalues  $\{\lambda_1, \dots, \lambda_n\}$ .

Furthermore,  $(\mathbf{A}\mathbf{u}_i) \cdot (\mathbf{A}\mathbf{u}_j) = \langle \mathbf{A}\mathbf{u}_i, \mathbf{A}\mathbf{u}_j \rangle = (\mathbf{A}\mathbf{u}_i)^T \mathbf{A}\mathbf{u}_j = \mathbf{u}_i^T \mathbf{A}^T \mathbf{A} \mathbf{u}_j = \lambda_j \mathbf{u}_i^T \mathbf{u}_j = \lambda_j \langle \mathbf{u}_i, \mathbf{u}_j \rangle$ .

In the case where  $i \neq j$ , this yields that  $\langle \mathbf{A}\mathbf{u}_i, \mathbf{A}\mathbf{u}_j \rangle = 0$ , i.e. that these images are orthogonal (or one or both could be  $\mathbf{0}$ ). In the case where  $i = j$ , this yields that  $\langle \mathbf{A}\mathbf{u}_j, \mathbf{A}\mathbf{u}_j \rangle = \|\mathbf{A}\mathbf{u}_j\|^2 = \lambda_j$ , so all of these eigenvalues must be greater than or equal to 0. Furthermore,  $\|\mathbf{A}\mathbf{u}_j\| = \sqrt{\lambda_j} = \sigma_j$  are the singular values. If we order the eigenvalues (and the singular values) in decreasing order, and if we create the orthogonal  $n \times n$  matrix

$\mathbf{P} = \begin{bmatrix} \uparrow & & \uparrow \\ \mathbf{u}_1 & \cdots & \mathbf{u}_n \\ \downarrow & & \downarrow \end{bmatrix}$  from the orthonormal basis for the domain and the  $m \times m$  matrix  $\mathbf{Q} = \begin{bmatrix} \uparrow & & \uparrow \\ \mathbf{w}_1 & \cdots & \mathbf{w}_m \\ \downarrow & & \downarrow \end{bmatrix}$  from the

orthonormal basis for the codomain, we can create the following commuting diagram describing of vectors are transformed relative to the standard bases and these preferred orthonormal bases:

$$\begin{array}{ccc} \{\mathbf{R}^n, \mathcal{E}_n\} & \xrightarrow{\mathbf{A}} & \{\mathbf{R}^m, \mathcal{E}_m\} \\ \mathbf{P} \uparrow & & \mathbf{Q} \uparrow \\ \{\mathbf{R}^n, \mathcal{B}\} & \xrightarrow{\Sigma} & \{\mathbf{R}^m, \mathcal{C}\} \end{array}$$

Since  $\mathbf{P}$  and  $\mathbf{Q}$  are orthogonal matrices,  $\mathbf{P}^{-1} = \mathbf{P}^T$  and  $\mathbf{Q}^{-1} = \mathbf{Q}^T$ , so we get  $\mathbf{A} = \mathbf{Q}\Sigma\mathbf{P}^T$ . This is known as the **Singular Value Decomposition** (SVD). If  $m = n$ , i.e. if  $\mathbf{A}$  is a square matrix, then the matrix  $\Sigma$  will be diagonal with the singular values on the diagonal. However the SVD also applies to any matrix – in which case the singular values will still appear along the “diagonal” starting at the upper-left position with 0's everywhere else.

**Example:** Consider the matrix  $\mathbf{A} = \begin{bmatrix} 6 & 2 \\ -7 & 6 \end{bmatrix}$ . We calculate  $\mathbf{A}^T \mathbf{A} = \begin{bmatrix} 6 & -7 \\ 2 & 6 \end{bmatrix} \begin{bmatrix} 6 & 2 \\ -7 & 6 \end{bmatrix} = \begin{bmatrix} 85 & -30 \\ -30 & 40 \end{bmatrix} = \mathbf{B}$ . This yields the eigenvalues (in decreasing order)  $\lambda_1 = 100$  and  $\lambda_2 = 25$ . These yield, respectively, the orthonormal basis vectors  $\mathbf{u}_1 = \frac{1}{\sqrt{5}} \begin{bmatrix} 2 \\ -1 \end{bmatrix}$ ,  $\mathbf{u}_2 = \frac{1}{\sqrt{5}} \begin{bmatrix} 1 \\ 2 \end{bmatrix}$ . We then calculate  $\mathbf{A}\mathbf{u}_1 = 10 \left( \frac{1}{\sqrt{5}} \begin{bmatrix} 1 \\ -2 \end{bmatrix} \right) = 10\mathbf{w}_1$ ,  $\mathbf{A}\mathbf{u}_2 = 5 \left( \frac{1}{\sqrt{5}} \begin{bmatrix} 2 \\ 1 \end{bmatrix} \right) = 5\mathbf{w}_2$ . This yields the orthogonal matrices  $\mathbf{P} = \frac{1}{\sqrt{5}} \begin{bmatrix} 2 & 1 \\ -1 & 2 \end{bmatrix}$  and  $\mathbf{Q} = \frac{1}{\sqrt{5}} \begin{bmatrix} 1 & 2 \\ -2 & 1 \end{bmatrix}$  and  $\mathbf{\Sigma} = \begin{bmatrix} 10 & 0 \\ 0 & 5 \end{bmatrix}$ .

**Example:** Consider the matrix  $\mathbf{A} = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 1 & 0 \end{bmatrix}$ . We calculate  $\mathbf{A}^T \mathbf{A} = \begin{bmatrix} 0 & 1 \\ 1 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 & 1 \\ 1 & 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 2 & 1 \\ 0 & 1 & 1 \end{bmatrix} = \mathbf{B}$ . This yields the eigenvalues (in decreasing order)  $\lambda_1 = 3$ ,  $\lambda_2 = 1$ , and  $\lambda_3 = 0$ . These yield, respectively, the orthonormal basis vectors  $\mathbf{u}_1 = \frac{1}{\sqrt{6}} \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$ ,  $\mathbf{u}_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$ , and  $\mathbf{u}_3 = \frac{1}{\sqrt{3}} \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$ . We then calculate  $\mathbf{A}\mathbf{u}_1 = \sqrt{3} \left( \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right) = \sqrt{3}\mathbf{w}_1$ ,

$\mathbf{A}\mathbf{u}_2 = 1 \left( \frac{1}{\sqrt{2}} \begin{bmatrix} -1 \\ 1 \end{bmatrix} \right) = 1\mathbf{w}_2$ , and  $\mathbf{A}\mathbf{u}_3 = \mathbf{0}$ . This yields the orthogonal matrices  $\mathbf{P} = \begin{bmatrix} \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{3}} \\ \frac{2}{\sqrt{6}} & 0 & -\frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{6}} & -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{3}} \end{bmatrix}$  and

$\mathbf{Q} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$  and  $\mathbf{\Sigma} = \begin{bmatrix} \sqrt{3} & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} = \begin{bmatrix} \sigma_1 & 0 & 0 \\ 0 & \sigma_2 & 0 \end{bmatrix}$ .

So  $\mathbf{A} = \mathbf{Q}\mathbf{\Sigma}\mathbf{P}^T = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} \sqrt{3} & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{6}} & \frac{2}{\sqrt{6}} & \frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{2}} & 0 & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{3}} & -\frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} \end{bmatrix}$  is the corresponding singular value decomposition.

**Notes by Robert Winters**