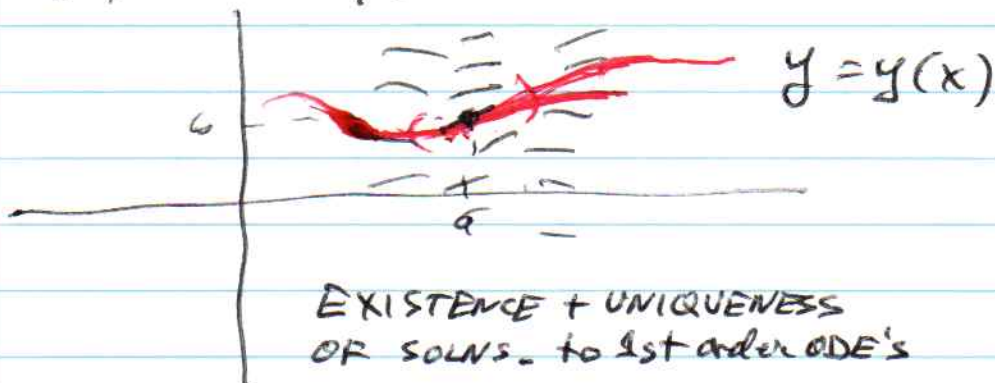


$$\frac{dy}{dx} = F(x, y)$$

[Lecture Notes #1, #2 used extensively during class.]



Integrating Factor [1st order Linear ODE's]

$$* \frac{dx}{dt} + P(t)x = f(t) \quad x(t)$$

$$\left[\frac{dy}{dx} + P(x)y = f(x) \right] \quad y(x)$$

Integrating factor $v = v(t)$

$$v \frac{dx}{dt} + \boxed{vP}x = v f$$

Product Rule: $\frac{d}{dt} [vx] = v \frac{dx}{dt} + \boxed{x \frac{dv}{dt}}$

WANT:

$$\frac{dv}{dt} = vP \quad \text{Separable}$$

$$\int \frac{dv}{v} = \int P dt \quad \ln v = \boxed{e^{\int P dt}}$$

$$\frac{d}{dt} [vx] = f(t) e^{\int P dt}$$

$t=0$ $x(a)$ given

use "dummy" variable

$$v x \Big|_a^t = \int_{u=a}^{u=t} g(u) e^{\int p dt} du$$

$$v(t) x(t) - v(a) x(a)$$

2nd Fund Prin of

$$x(t) = \left[e^{-\int p dt} \left[\int_a^t g(u) e^{\int p dt} du + v(a) x(a) \right] \right]$$

Calculus.

Formula possible for soln, in terms of a definite integral. see Revised Notes #1

Input-Response Formulation [Linear ODE's]

$$\frac{d^n x}{dt^n} + p_{n-1}(t) \frac{d^{n-1} x}{dt^{n-1}} + \dots + p_1(t) \frac{dx}{dt} + p_0(t) x = g(t)$$

System

Input

SOLUTION: $x(t)$ Response

BANKING: $x = x(t)$ \$ in bank, Rate I

$$\frac{dx}{dt} = Ix \quad x(0) = x_0 \text{ Initial Amount}$$

MAKE payment / WITHDRAWALS

$$\frac{dx}{dt} = Ix + g(t)$$

$g(t)$ RATE of deposit / with drawal

$$\frac{dx}{dt} - Ix = g(t)$$

System
Input

DIFFUSION: Newton's Law of Cooling.
 $y(t)$ outside temp.



$x(t)$ internal temp.

$$\frac{dx}{dt} = K(y-x)$$

$$K > 0$$

K coupling constant.

$$\frac{dx}{dt} = Ky - Kx$$

$$\frac{dx}{dt} + Kx = Ky(t)$$

1st order, Linear

system

Input.

If $y(t)$ sinusoidal

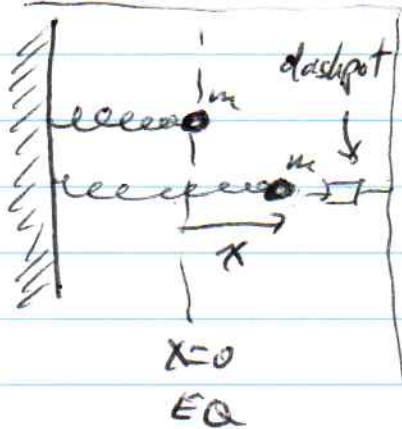
Expect $x(t)$ Respond sinusoidal.



Expect Lag in response

RAPID VARIATION \rightarrow Low Response Amplitude.

Hooke's Law + oscillation.



MASS-SPRING-DASHPOT w/ External force

$$F = -kx \text{ Hooke's Law.}$$

ADD FRICTION

$$F = -kx - cV \text{ w/ friction.}$$

Apply external force

$$F = -kx - cV + F_{ext}$$

Newton $F = ma$ $a = \frac{dv}{dt}$ $v = \frac{dx}{dt}$

$$ma = -kx - cV + F_{ext}$$

$$\dot{x} = \frac{dx}{dt}$$

$$m \frac{d^2x}{dt^2} = -kx - c \frac{dx}{dt} + F_{ext}$$

$$\ddot{x} = \frac{d^2x}{dt^2}$$

$$m \frac{d^2x}{dt^2} + c \frac{dx}{dt} + kx = F_{ext}$$

$$m \ddot{x} + c \dot{x} + kx = F_{ext}$$

$$\ddot{x} + \frac{c}{m} \dot{x} + \frac{k}{m} x = \frac{F_{ext}}{m}$$

2nd order ODE, LINEAR, Inhomogeneous

System

Input

$x(t)$ Response

See Lecture Notes for additional details.