

## Concourse Math 18.02 – Some useful facts

**Basic Chain Rule:**  $\frac{d}{dt}[f(x(t), y(t))] = \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt} = \nabla f \cdot \mathbf{v}$  for a path in  $\mathbf{R}^2$ ;

$$\frac{d}{dt}[f(x(t), y(t), z(t))] = \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt} + \frac{\partial f}{\partial z} \frac{dz}{dt} = \nabla f \cdot \mathbf{v} \text{ for a path in } \mathbf{R}^3.$$

**Directional Derivative** of a function  $f$  in the direction  $\mathbf{u}$  (unit vector):  $D_{\mathbf{u}}f = \nabla f \cdot \mathbf{u}$

**Fundamental Theorem of Line Integrals:** If  $V$  is differentiable and  $C$  is a curve from point  $\mathbf{x}_0$  to point  $\mathbf{x}_1$ , then  $\int_C \nabla V \cdot d\mathbf{r} = V(\mathbf{x}_1) - V(\mathbf{x}_0)$ .

**Green's Theorem:** If  $P(x, y)$  and  $Q(x, y)$  are differentiable with continuous 1<sup>st</sup> partial derivatives through a bounded region  $D$  in  $\mathbf{R}^2$  and if  $C$  is the boundary of  $D$  oriented in the counterclockwise sense, then

$$\oint_C P(x, y) dx + Q(x, y) dy = \iint_D \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA.$$

**Curl and Divergence:** If  $\mathbf{F}(x, y, z) = \langle P(x, y, z), Q(x, y, z), R(x, y, z) \rangle$  is a vector field in  $\mathbf{R}^3$  with differentiable

component functions, then  $\text{curl } \mathbf{F} = \left\langle \frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z}, \frac{\partial P}{\partial z} - \frac{\partial R}{\partial x}, \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right\rangle$  and  $\text{div } \mathbf{F} = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}$ .

**Divergence Theorem:** If the components of the vector field  $\mathbf{F}$  are differentiable with continuous 1<sup>st</sup> partial derivatives through a bounded region  $B$  in  $\mathbf{R}^3$  and if  $S$  is the boundary of  $B$  oriented with unit outward normal vector  $\mathbf{n}$ , then  $\oiint_S \mathbf{F} \cdot d\mathbf{S} = \oiint_S (\mathbf{F} \cdot \mathbf{n}) dS = \iiint_B (\text{div } \mathbf{F}) dV$ .

**Stokes' Theorem:** If the components of the vector field  $\mathbf{F}$  are differentiable with continuous 1<sup>st</sup> partial derivatives through a surface  $S$  in  $\mathbf{R}^3$  oriented with unit normal vector  $\mathbf{n}$  and if  $C$  is the boundary of  $S$  oriented counterclockwise relative to  $\mathbf{n}$ , then  $\oint_C \mathbf{F} \cdot d\mathbf{r} = \iint_S (\text{curl } \mathbf{F}) \cdot \mathbf{n} dS = \iint_S (\text{curl } \mathbf{F}) \cdot d\mathbf{S}$ .

**Surface integration “toolkits”:**

**Sphere of radius  $R$ :**  $\begin{cases} x = R \cos \theta \sin \phi \\ y = R \sin \theta \sin \phi \\ z = R \cos \phi \end{cases}$ ,  $\mathbf{n} = \frac{\langle x, y, z \rangle}{R}$ ,  $dS = R^2 \sin \phi d\phi d\theta$ ,  $x^2 + y^2 + z^2 = R^2$

**Cylinder of radius  $R$ :**  $\begin{cases} x = R \cos \theta \\ y = R \sin \theta \\ z = z \end{cases}$ ,  $\mathbf{n} = \frac{\langle x, y, 0 \rangle}{R}$ ,  $dS = R dz d\theta$ ,  $x^2 + y^2 = R^2$

**Graph of  $f(x, y)$ :**  $\begin{cases} x = x \\ y = y \\ z = f(x, y) \end{cases}$ ,  $\mathbf{n} = \frac{\langle -f_x, -f_y, 1 \rangle}{\sqrt{1 + f_x^2 + f_y^2}}$ ,  $dS = \frac{dx dy}{|\mathbf{n} \cdot \mathbf{k}|} = \sqrt{1 + f_x^2 + f_y^2} dx dy$

**General parameterized surface:**  $\mathbf{r}(s, t) = \langle x(s, t), y(s, t), z(s, t) \rangle$ ,  $dS = \left\| \frac{\partial \mathbf{r}}{\partial s} \times \frac{\partial \mathbf{r}}{\partial t} \right\| ds dt$ ,  $d\mathbf{S} = \left( \frac{\partial \mathbf{r}}{\partial s} \times \frac{\partial \mathbf{r}}{\partial t} \right) ds dt$

**Geometry formulas:** Volume of a ball of radius  $R$ :  $= \frac{4}{3} \pi R^3$ ; Surface area of a sphere of radius  $R$ :  $= 4\pi R^2$

**Useful identities:**  $\cos^2 \theta = \frac{1 + \cos 2\theta}{2}$ ,  $\sin^2 \theta = \frac{1 - \cos 2\theta}{2}$ ,  $\sin^2 \theta + \cos^2 \theta = 1$